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For R a fixed set of representatives for G/H, the map

$$\varphi_R \colon \operatorname{Ind}_H^G(S_{\widetilde{D}}) \to S_{\overline{D}}$$
$$f \mapsto \{f(r)\}_{r \in R}$$

is well-defined by *H*-equivariance of the elements of $S_{\widetilde{D}}$ and one checks that it defines a *G*-equivariant isometric bijection. Similarly for the adjoint operators.

The following example is a particular case of the previous lemma.

EXAMPLE 3.2. Let us look at the case $\widetilde{M} = M \times G$. A section $\widetilde{s} \in C_c^{\infty}(\widetilde{M}, \pi^*E)$ is an element $\widetilde{s} = \{s_g\}_{g \in G}$ where $s_g \in C^{\infty}(M, E)$ and $s_g = 0$ for all but finitely many g's. Note that $L^2(\widetilde{M}, \pi^*E)$ can be identified with $\ell^2(G) \otimes L^2(M, E)$. Now

$$\widetilde{D}\,\widetilde{s} = \{Ds_g\}_{g\in G} \in C^{\infty}_c(\widetilde{M}, \pi^*F)$$

and hence $S_{\widetilde{D}}$ may be identified with $\ell^2(G) \otimes S_D \cong \ell^2(G)^d$, where $d = \dim_{\mathbb{C}}(S_D)$. In this identification the projection P onto $S_{\widetilde{D}}$ becomes the identity in $M_d(\mathcal{N}(G))$ and thus

$$\dim_G(S_{\widetilde{D}}) = \sum_{i=1}^d \langle e, e \rangle = d = \dim_{\mathbf{C}}(S_D).$$

A similar argument for D^* shows that in this case not only does the L^2 -Index of \widetilde{D} coincide with the Index of D, but also the individual terms of the difference correspond to each other. This is not the case in general, see Example 2.2.

4. On K-homology

Many ideas of this section go back to the seminal article by Baum and Connes [3], which has been circulating for many years and has only recently been published.

An elliptic pseudo-differential operator D on the closed manifold M can also be used to define an element $[D] \in K_0(M)$, the K-homology of M, and according to Baum and Douglas [4], all elements of $K_0(M)$ are of the form [D]. The index defined in Section 2 extends to a well-defined homomorphism (cf. [4])

Index: $K_0(M) \rightarrow \mathbb{Z}$,

such that $\operatorname{Index}([D]) = \operatorname{Index}(D)$. On the other hand, the projection $\operatorname{pr}: M \to \{pt\}$ induces, after identifying $K_0(\{pt\})$ with \mathbb{Z} , a homomorphism

(*)
$$\operatorname{pr}_* \colon K_0(M) \to \mathbf{Z},$$

which, as explained in [4], satisfies

 $\operatorname{pr}_*([D]) = \operatorname{Index}([D]).$

More generally (cf. [4]), for a not necessarily finite CW-complex X, every $x \in K_0(X)$ is of the form $f_*[D]$ for some $f: M \to X$, and $K_0(X)$ is obtained as a colimit over $K_0(M_\alpha)$, where the M_α form a directed system consisting of closed Riemannian manifolds (these homology groups $K_0(X)$ are naturally isomorphic to the ones defined using the Bott spectrum; sometimes, they are referred to as *K*-homology groups with *compact supports*). The index map from above extends to a homomorphism

Index: $K_0(X) \rightarrow \mathbb{Z}$,

such that $\operatorname{Index}(x) = \operatorname{Index}([D])$ if $x = f_*[D]$, with $f: M \to X$.

We now consider the case of X = BG, the classifying space of the discrete group G, and obtain thus for any $f: M \to BG$ a commutative diagram

$$\begin{array}{cccc} K_0(M) & \stackrel{\operatorname{Index}}{\longrightarrow} & \mathbf{Z} \\ & & & & \\ f_* \downarrow & & & \\ K_0(BG) & \stackrel{\operatorname{Index}}{\longrightarrow} & \mathbf{Z} \end{array}.$$

Note that (*) from above implies the following naturality property for the index homomorphism.

LEMMA 4.1. For any homomorphism $\varphi: H \to G$ one has a commutative diagram



We now turn to the L^2 -index of Section 2. It extends to a homomorphism

Index_G: $K_0(BG) \rightarrow \mathbf{R}$

as follows. Each $x \in K_0(BG)$ is of the form $f_*(y)$ for some $y = [D] \in K_0(M)$, $f: M \to BG$, M a closed smooth manifold and D an elliptic operator on M. Let \widetilde{D} be the lifted operator to \widetilde{M} , the G-covering space induced by $f: M \to BG$. Then put

 $\operatorname{Index}_G(x) := \operatorname{Index}_G(\widetilde{D}).$

One checks that $\operatorname{Index}_G(x)$ is indeed well-defined, either by direct computation, or by identifying it with $\tau(x)$, where τ denotes the composite of the assembly map $K_0(BG) \to K_0(C_r^*G)$ with the natural trace $K_0(C_r^*G) \to \mathbb{R}$ (for this latter point of view, see Higson-Roe [10]; for a discussion of the assembly map see e.g. Kasparov [12], or Valette [14]). The following naturality property of this index map is a consequence of Lemma 3.1.

LEMMA 4.2. For H < G the following diagram commutes:



Atiyah's L^2 -Index Theorem 2.1 for a given G can now be expressed as the statement (as already observed in [10])

Index_G = Index:
$$K_0(BG) \rightarrow \mathbf{R}$$
.

5. Algebraic proof of Atiyah's L^2 -index theorem

Recall that a group A is said to be *acyclic* if $H_*(BA, \mathbb{Z}) = 0$ for * > 0. For G a countable group, there exists an embedding $G \to A_G$ into a countable acyclic group A_G . There are many constructions of such a group A_G available in the literature, see for instance Kan-Thurston [11, Proposition 3.5], Berrick-Varadarajan [5] or Berrick-Chatterji-Mislin [6]; these different constructions are to be compared in Berrick's forthcoming work [7]. It follows that the suspension ΣBA_G is contractible, and therefore the inclusion $\{e\} \to A_G$